

Efficient multi-image deconvolution in astronomy

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Abstract

The deconvolution of astronomical images by the Richardson-Lucy method (RLM) is extended here to the problem of multiple image deconvolution and the reduction of boundary effects. We show the multiple image RLM in its accelerated gradient-version SGP (Scaled Gradient Projection). Numerical simulations indicate that the approach can provide excellent results with a considerable reduction of the boundary effects. Also exploiting GPUlib applied to the IDL code, we obtained a remarkable acceleration of up to two orders of magnitude [Prato et al. 2012].

Multiple image deconvolution problem

Multiple image deconvolution problem with Poisson data:

$$\min_{\vec{f} \geq 0} J_0(\vec{f}; \vec{g}) = \sum_{j=1}^p \sum_{\mathbf{m} \in S} \{ \vec{g}_j(\mathbf{m}) \ln \frac{\vec{g}_j(\mathbf{m})}{(A_j \vec{f})(\mathbf{m}) + \vec{b}_j(\mathbf{m})} + (A_j \vec{f})(\mathbf{m}) + \vec{b}_j(\mathbf{m}) - \vec{g}_j(\mathbf{m}) \} \quad (1)$$

where:

- ▶ \vec{f} is the unknown object;
- ▶ \vec{g}_j ($j = 1, \dots, p$) are the detected images;
- ▶ $A_j \vec{f} = \vec{K}_j * \vec{f}$ ($j = 1, \dots, p$), where \vec{K}_j is the j -th PSF, normalized to unit volume;
- ▶ \vec{b}_j ($j = 1, \dots, p$) are the background emissions;
- ▶ S is the image domain.

From the standard expectation maximization method [Shepp & Vardi 1982] applied to this problem, we obtain the *multiple image* RL method

$$\vec{f}^{(k+1)} = \frac{\vec{f}^{(k)}}{p} \sum_{j=1}^p A_j^T \frac{\vec{g}_j}{A_j \vec{f}^{(k)} + \vec{b}_j} \quad (2)$$

Since

$$\nabla J_0(\vec{f}; \vec{g}) = \sum_{j=1}^p \left\{ \vec{1} - A_j^T \frac{\vec{g}_j}{A_j \vec{f} + \vec{b}_j} \right\} \quad (3)$$

algorithm (2) can be seen as a scaled gradient method, with a scaling given, at iteration k , by $\vec{f}^{(k)}/p$. Therefore the application of SGP [Bonettini et al. 2009] to this problem is straightforward.

Boundary effect correction

If the target \vec{f} is not completely contained in the image domain, the previous deconvolution method produce annoying boundary artifacts.

Idea: reconstruct the object \vec{f} over a broader domain $R \supset S$. If we introduce:

- ▶ an array \vec{S} containing R and S and such that Fourier transform in \vec{S} can be computed by FFT;
- ▶ the masks \vec{M}_R, \vec{M}_S , defined over \vec{S} , which are 1 over R, S respectively and 0 outside;
- ▶ the matrices A_j and A_j^T ($j = 1, \dots, p$) defined as

$$(A_j \vec{f})(\mathbf{m}) = \vec{M}_S(\mathbf{m}) \sum_{\mathbf{n} \in \vec{S}} \vec{K}_j(\mathbf{m} - \mathbf{n}) \vec{M}_R(\mathbf{n}) \vec{f}(\mathbf{n}) \quad (4)$$

$$(A_j^T \vec{g}_j)(\mathbf{n}) = \vec{M}_R(\mathbf{n}) \sum_{\mathbf{m} \in \vec{S}} \vec{K}_j(\mathbf{m} - \mathbf{n}) \vec{M}_S(\mathbf{m}) \vec{g}_j(\mathbf{m}) \quad (5)$$

where \vec{K}_j, \vec{g}_j ($j = 1, \dots, p$) have been extended to \vec{S} by zero padding, then $J_0(\vec{f}; \vec{g})$ is given again by (1), with S replaced by \vec{S} , while its gradient is now given by

$$\nabla J_0(\vec{f}; \vec{g}) = \sum_{j=1}^p \left\{ A_j^T \vec{1} - A_j^T \frac{\vec{g}_j}{A_j \vec{f} + \vec{b}_j} \right\} \quad (6)$$

The domain R can be defined through the functions

$$\vec{\alpha}_j(\mathbf{n}) = (A_j^T \vec{1})(\mathbf{n}) \quad , \quad \vec{n} \in \vec{S} \quad (7)$$

$$\vec{\alpha}(\mathbf{n}) = \sum_{j=1}^p \vec{\alpha}_j(\mathbf{n}) \quad .$$

in the following way:

$$R = \{ \vec{n} \in \vec{S} \mid \vec{\alpha}_j(\vec{n}) \geq \sigma; j = 1, \dots, p \} \quad (8)$$

where σ is a thresholding value. Then the RL algorithm, with boundary effect correction, is given by

$$\vec{f}^{(k+1)} = \frac{\vec{M}_R \vec{f}^{(k)}}{\vec{\alpha}} \sum_{j=1}^p A_j^T \frac{\vec{g}_j}{A_j \vec{f}^{(k)} + \vec{b}_j} \quad (9)$$

the quotient being zero in the pixels outside R .

Numerical results

Comparison between:

- ▶ Multiple RLM
- ▶ SGP

For testing the accuracy of the deconvolution method with boundary effect correction we apply "inverse crime" on an image of nebula NGC7027. The image is partitioned into 4 partially overlapping sub-images, the methods with boundary effect correction are applied and the final reconstruction is obtained as a mosaic of the four partial reconstructions.

Test setting:

- true object: NGC7027 nebula
- blurring: 3 PSF generated according to LINC-NIRVANA [Herbst et al. 2003] model and with equispaced orientations of the baseline ($0^\circ, 60^\circ, 120^\circ$)

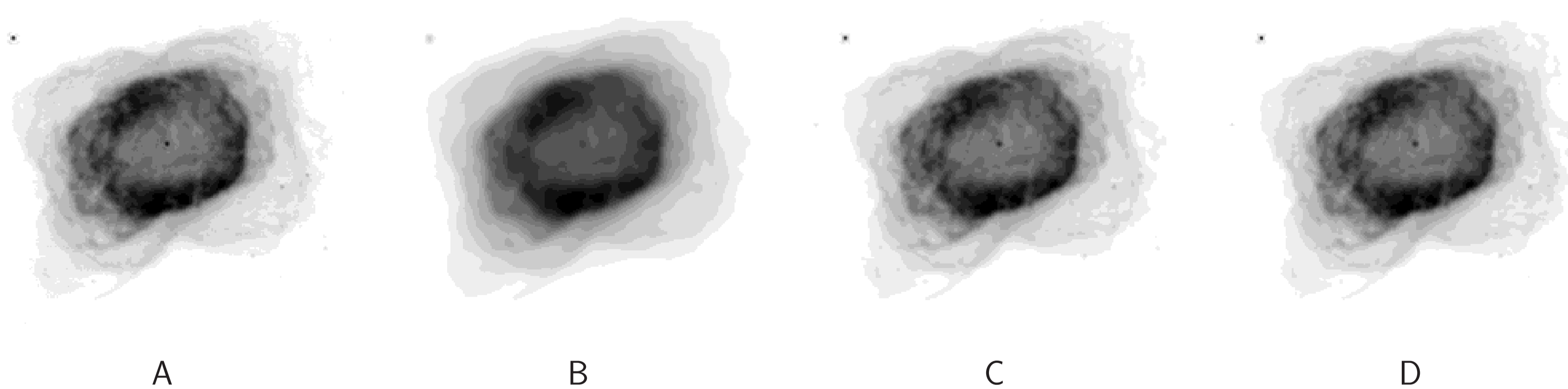


Figure: A: Original Nebula, B: its blurred and noisy image in the case $m = 10$ and baseline orientation 0° ; C: reconstruction of the global image; D: reconstruction as a mosaic of four reconstructions of partially overlapping sub-domains, using the algorithms with boundary effect correction.

Table: Reconstruction of the Nebula

$m = 10$					
Algorithm	It	Err	Sec	SpUp	AlgSpUp
RL	2899	0.034	13978	-	-
RL_CUDA	2899	0.034	174.2	80.2	-
SGP	160	0.034	873.3	-	16.0
SGP_CUDA	160	0.034	15.45	56.5	-
$m = 15$					
Algorithm	It	Err	Sec	SpUp	AlgSpUp
RL	243	0.094	1174	-	-
RL_CUDA	243	0.094	15.28	76.8	-
SGP	11	0.087	69.88	-	16.8
SGP_CUDA	11	0.086	1.532	45.6	-

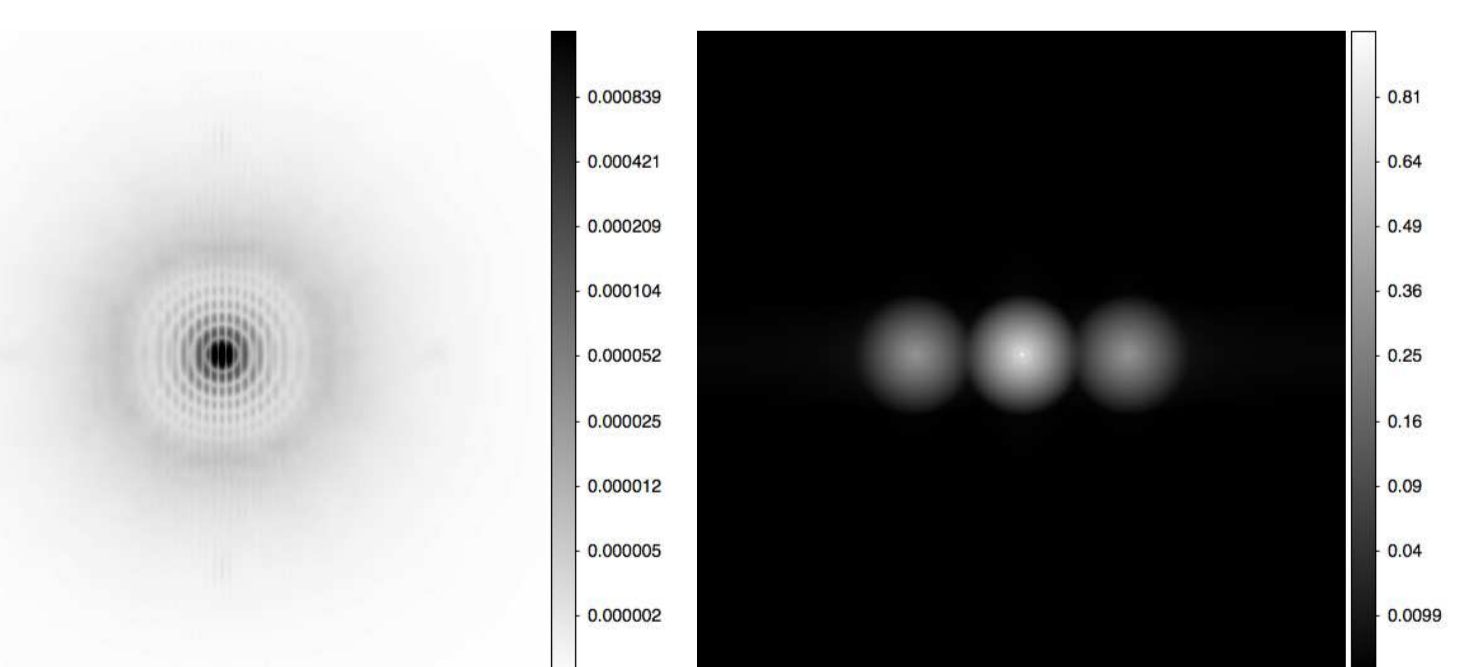


Figure: Simulated PSF of LINC-NIRVANA with SR = 70% (left panel) and corresponding MTF (right panel)

References

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